

The differential inclusion modeling FISTA algorithm and optimality in the case $b < 3$

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The minimization problem

$$\min\{F(x) : x \in \mathcal{H}\} \quad (\text{P})$$

- $\mathcal{H} = \mathbb{R}^d$, $d \geq 1$.
- $F = f + g : \mathcal{H} \rightarrow \overline{\mathbb{R}}$, where :
 - $f : \mathcal{H} \rightarrow \mathbb{R}$ proper, convex, differentiable with ∇f L -Lipschitz
 - $g : \mathcal{H} \rightarrow \overline{\mathbb{R}}$ proper, convex, lower semi-continuous.
- $x^* \in \arg \min\{F\} \neq \emptyset$

$$\text{Solutions of (P) :} \quad \{\nabla f(x)\} + \partial g(x) = \partial F(x) \ni 0$$

Dynamical system

$$\ddot{x}(t) + \frac{b}{t}\dot{x}(t) + \partial F(x(t)) \ni 0 \quad (\text{DI})$$

where $b > 0$.

Discretization of (DI)-FISTA (Su et al '15, Attouch et al '16)

Time step : $h > 0$

Explicit discretization with respect to ∇f

Implicit discretization with respect to ∂g

Algorithm 1 FISTA (Beck '09 et al, Nesterov '83/'04)

Let $x_0, x_1 \in \mathbb{R}^d$ and $\gamma = h^2$. For all $n \geq 1$, define $\{x_n\}_{n \in \mathbb{N}}$, $\{y_n\}_{n \in \mathbb{N}}$ as follows :

$$\begin{aligned} y_n &= x_n + \frac{n}{n+b}(x_n - x_{n-1}) \\ x_{n+1} &= \text{Prox}_{\gamma g}(y_n - \gamma \nabla f(y_n)) \\ &= (\text{Id} + \partial \gamma g)^{-1}(y_n - \gamma \nabla f(y_n)) \end{aligned} \tag{1}$$

$$\text{Prox}_{\gamma g}(x) = (\text{Id} + \partial \gamma g)^{-1}(x) = \arg \min \left\{ g(y) + \frac{\|x - y\|^2}{2\gamma} \right\}$$

The differential setting

If g differentiable and \mathcal{H} possibly infinite dimensional :

$$(DI) \quad \Leftrightarrow \quad \ddot{x}(t) + \frac{b}{t}\dot{x}(t) + \nabla F(x(t)) = 0 \quad (DE)$$

Theorem (Asymptotic properties for (DE) : Su et al.'15, Attouch et al '15/'16/'17, May '16, Aujol et al'17)

If $b < 3$:

$$F(x(t)) - F(x^*) \sim O\left(t^{-\frac{2b}{3}}\right) , \quad \|\dot{x}(t)\| \sim O(t^{-p}) , \forall p < \frac{2b}{3} \quad (2)$$

$$\text{If } b \geq 3 : \quad F(x(t)) - F(x^*) \sim O(t^{-2}) , \quad \|\dot{x}(t)\| \sim O(t^{-1}) \quad (3)$$

If $b > 3$:

$$F(x(t)) - F(x^*) \sim o(t^{-2}) , \quad \|\dot{x}(t)\| \sim o(t^{-1}) , \quad x(t) \rightarrow x^* \quad (4)$$

The differential inclusion

For $t_0 > 0$, $b > 0$ and $t \geq t_0$:

$$\begin{cases} \ddot{x}(t) + \frac{b}{t}\dot{x}(t) + \partial F(x(t)) \ni 0 \\ x(t_0) = x_0 \quad \dot{x}(t_0) = v_0 \end{cases} \quad (\text{DI})$$

General framework for (DI) (Paoli 2000)

$$\begin{cases} \ddot{x}(t) + \partial F(x(t)) \ni h(t, x(t), \dot{x})(t) \\ x(t_0) = x_0 \quad \dot{x}(t_0) = v_0 \end{cases} \quad (\text{GDI})$$

where h is Lipschitz continuous in its last two arguments uniformly with respect to the first one.

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Definition (Shock solution of (DI) Paoli '00, Attouch et al '02)

A function $x : [t_0, +\infty) \rightarrow \mathbb{R}^d$ is an **energy-conserving shock solution** of (DI) if :

- 1 $x \in C^{0,1}([t_0, T]; \mathbb{R}^d)$, for all $T > t_0$
- 2 $\dot{x} \in BV([t_0, T]; \mathbb{R}^d)$, for all $T > t_0$
- 3 $x(t) \in \mathcal{D}(F)$, for all $t \geq t_0$
- 4 For all $\phi \in C_c^1([t_0, +\infty), \mathbb{R}^+)$ and $v \in C([t_0, +\infty), \mathcal{D}(F))$, it holds :

$$\int_{t_0}^T (F(x(t)) - F(v(t)))\phi(t)dt \leq \langle \ddot{x} + \frac{b}{t}\dot{x}, (v - x)\phi \rangle_{M \times C} \quad (5)$$

- 5 x satisfies the following energy equation for a.e. $t \geq t_0$

$$F(x(t)) - F(x_0) + \frac{1}{2}\|\dot{x}(t)\|^2 - \frac{1}{2}\|v_0\|^2 + \int_{t_0}^t \frac{b}{s}\|\dot{x}(s)\|^2 ds = 0 \quad (6)$$

Approximating ODE

We consider the Moreau-Yosida approximation of F , $\{F_\gamma\}_{\gamma>0}$ and the following approximating ODE :

Approximating ODE

$$\begin{aligned}\ddot{x}_\gamma(t) + \frac{b}{t}\dot{x}_\gamma(t) + \nabla F_\gamma(x_\gamma(t)) &= 0 \\ x_\gamma(t_0) = x_0 \quad \dot{x}_\gamma(t_0) &= v_0\end{aligned}\tag{ADE}$$

(ADE) falls into the classical theory of differential equations and admits a unique solution $x_\gamma \in \mathcal{C}^2([t_0, +\infty); \mathbb{R}^d)$, for all $\gamma > 0$.

Existence of a shock solution

Theorem

Let $\{F_\gamma\}_{\gamma>0}$ the Moreau-Yosida approximations of F . There exists a subsequence $\{x_\gamma\}_{\gamma>0}$ of solutions of (ADE) that converges to a shock solution of (DI), according to the following scheme :

- $x_\gamma \xrightarrow{\gamma \rightarrow 0} x$ uniformly on $[t_0, T], \forall T > t_0$
- $\dot{x}_\gamma \xrightarrow{\gamma \rightarrow 0} \dot{x}$ in $L^p([t_0, T]; \mathbb{R}^d)$, $\forall p \in [1, +\infty)$, $\forall T > t_0$ **(AS)**
- $F_\gamma(x_\gamma) \xrightarrow{\gamma \rightarrow 0} F(x)$ in $L^p([t_0, T]; \mathbb{R}^d)$, $\forall p \in [1, +\infty)$, $\forall T > t_0$

Lemma (A-priori estimates)

$$\sup_{\gamma>0} \{ \|x_\gamma\|_\infty, \|\dot{x}_\gamma\|_\infty, \|\nabla F_\gamma(x_\gamma)\|_1, \|\ddot{x}_\gamma\|_1 \} < +\infty$$

The case of $\mathcal{D}(F) = \mathbb{R}^d$

Lemma (2^{nd} order a-priori estimate)

If $\mathcal{D}(F) = \mathbb{R}^d$, we additionally have : $\sup_{\gamma > 0} \{ \|\ddot{x}_\gamma\|_\infty \} < +\infty$

Corollary

If $\mathcal{D}(F) = \mathbb{R}^d$, then the differential inclusion (DI) admits a shock solution x , such that :

$$x \in W^{2,\infty}((t_0, T); \mathbb{R}^d) \cap C^1([t_0, +\infty); \mathbb{R}^d), \text{ for all } T > t_0.$$

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Asymptotic analysis

Let x be a shock solution of (DI) obtained as a limit of the approximation scheme (\mathcal{AS}) and x^* a minimizer of F .

Notation : $W(t) = F(x(t)) - F(x^*)$

For all $\lambda, \xi \geq 0$ we consider the Lyapunov function :

$$\mathcal{E}_{\lambda, \xi}(t) = t^2 W(t) + \frac{1}{2} \|\lambda(x(t) - x^*) + t\dot{x}(t)\|^2 + \frac{\xi}{2} \|x(t) - x^*\|^2$$

Lemma

For $b \geq 3$, $2 \leq \lambda \leq b - 1$ and $\xi = \lambda(b - \lambda - 1)$, $\mathcal{E}_{\lambda, \xi}$ is **essentially non-increasing** in $[t_0, +\infty)$:

$$\mathcal{E}_{\lambda, \xi}(t) \leq \mathcal{E}_{\lambda, \xi}(s), \quad \text{for a.e. } t_0 \leq s \leq t$$

Convergence rates for $W(t)$ and $\dot{x}(t)$

Theorem (A. et al.'17)

Let x be a shock solution of (DI) obtained as a limit of the approximation scheme (**AS**) and x^* a minimizer of F . There exist $C_1, C_2 > 0$, s.t. :

- If $b \geq 3$:

$$\sup_{t \geq t_0} \{\|x(t) - x^*\|\} < +\infty \quad (7)$$

$$W(t) \leq \frac{C_1}{t^2} \quad \text{and} \quad \|\dot{x}(t)\| \leq \frac{C_2}{t} \quad \text{for a.e. } t \geq t_0 \quad (8)$$

- If $b > 3$: $\int_{t_0}^{+\infty} tW(t)dt < +\infty$ and $\int_{t_0}^{+\infty} t\|\dot{x}(t)\|^2 dt < +\infty$
 - The trajectory $\{x(t)\}_{t \geq t_0}$ converges asymptotically to x^* .

$$\text{ess lim}_{t \rightarrow \infty} t^2 W(t) = 0 \quad \text{and} \quad \text{ess lim}_{t \rightarrow \infty} t \|\dot{x}(t)\| = 0 \quad (9)$$

The case of low friction $b < 3$

For $\lambda = \frac{2b}{3}$, $\xi = \frac{2b(3-b)}{9} > 0$ and $c = 2 - \frac{2b}{3} > 0$, for all $t \geq t_0$, we consider the energy-function :

$$\mathcal{H}(t) = t^{-c} \mathcal{E}_{\lambda, \xi}(t)$$

$$= t^{-c} \left(W(t) + \frac{1}{2} \left\| \frac{2b}{3} (x(t) - x^*) + t\dot{x}(t) \right\|^2 + \frac{2b(3-b)}{3} \|x(t) - x^*\|^2 \right)$$

Lemma

For $b \leq 3$, \mathcal{H} is essentially non-increasing in $[t_0, +\infty)$

Corollary (A. et al.'17)

Let $b < 3$, x a shock solution of (DI) obtained as a limit of the approximation scheme (\mathcal{AS}) and x^* a minimizer of F .

$$W(t) \leq Ct^{-\frac{2b}{3}} \quad \text{for a.e. } t \geq t_0 \quad (10)$$

Bound estimates when $\mathcal{D}(F) = \mathbb{R}^d$

Let $x \in W^{2,\infty}((t_0, T); \mathbb{R}^d) \cap C^1([t_0, +\infty); \mathbb{R}^d)$, for all $T > t_0$ a solution of (DI) with $\mathcal{D}(F) = \mathbb{R}^d$.

Key-property

\dot{x} , W , $\mathcal{E}_{\lambda,\xi}$, \mathcal{H} are *locally absolutely continuous functions*

Lemma (Generalized derivation rule (Brezis '73))

$$\frac{d}{dt}(F(x(t))) = \langle z, \dot{x}(t) \rangle \quad \forall z \in \partial F(x(t)) \quad \text{a.e. in } (t_0, T), \forall T > t_0$$

The energies $\mathcal{E}_{\lambda,\xi}$ and \mathcal{H} are non-increasing in $[t_0, +\infty)$ (for suitable values of λ and ξ).

Bound estimates when $\mathcal{D}(F) = \mathbb{R}^d$

Corollary (A. et al.'17)

Let $x \in W^{2,\infty}((t_0, T); \mathbb{R}^d) \cap C^1([t_0, +\infty); \mathbb{R}^d)$, for all $T > t_0$ be a solution of (DI) with $\mathcal{D}(F) = \mathbb{R}^d$. There exists $C > 0$, s.t. **for all** $t \geq t_0$:

- $b < 3$: $W(t) \leq Ct^{-\frac{2b}{3}}$ and $\|\dot{x}(t)\| \leq (C + \sup_{t \geq t_0} \{\|x(t)\|\})t^{-\frac{b}{3}}$
- $b \geq 3$: $\sup_{t \geq t_0} \{\|x(t)\|\} < +\infty$, $W(t) \leq Ct^{-2}$, $\|\dot{x}(t)\| \leq Ct^{-1}$
- $b > 3$: $W(t) \sim o(t^{-2})$, $\|\dot{x}(t)\| \sim o(t^{-1})$, $x(t) \rightarrow x^*$

Proofs : Well adapted to the differential setting thanks to the absolute continuity property.

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Optimal convergence rate for $W(t)$ when $b < 3$

We consider $F(x) = |x|$, for all $x \in \mathbb{R}$ and study (DI) for $b < 3$.

Theorem (A. et al.'17)

Let x be a solution of (DI), with $F(x) = |x|$ and $b < 3$ such that $x(t_0) \neq 0$. There exists a constant $K > 0$, such that for any $T > t_0$, there exists $t > T$ such that :

$$W(t) = |x(t)| \geq \frac{K}{t^{\frac{2b}{3}}} \quad (11)$$

We have that $x^* = 0$ and

$$W(t) = F(x(t)) - F(x^*) = |x(t)| = z(t)x(t) \quad \text{with } z(t) \in \partial F(x(t)) \quad (\text{P1-H})$$

Lemma

Let $b < 3$ and x a solution to (DI) with $F(x) = |x|$, such that $x(t_0) = x_0 \neq 0$. Then $\exists K_1 > 0$ s.t. $\mathcal{H}(t) \geq K_1$.

Proof : For $\lambda = \frac{2b}{3}$, $\xi = \frac{2b(3-b)}{9} > 0$ and $c = 2 - \frac{2b}{3} > 0$, for all $t \geq t_0$

$$\mathcal{H}(t) = t^{-c}(t^2|x(t)| + \frac{1}{2}|\lambda x(t) + t\dot{x}(t)|^2 + \frac{\xi}{2}|x(t)|^2)$$

By differentiating \mathcal{H} and using (P1-H) :

$$\begin{aligned}\dot{\mathcal{H}}(t) &= -\frac{2b(9-b^2)}{27}t^{-c-1}|x(t)|^2 \\ &\geq C_0 t^{c-5}\mathcal{H}(t) \quad \text{a.e. in } (t_0, +\infty)\end{aligned}$$

with $c = 2 - \frac{2b}{3} \in (0, 2)$.

It follows that : $\mathcal{H}(t) \geq K_1$, where $K_1 = \mathcal{H}(t_0)e^{C_0 t_0^{c-4}}$

Proof of Optimality : From Lemma :

$$t^2|x(t)| + \underbrace{\frac{1}{2}|\lambda x(t) + t\dot{x}(t)|^2 + \frac{\xi}{2}|x(t)|^2}_{=v(t)} = \mathcal{E}_{\lambda,\xi}(t) = \mathcal{H}(t)t^c \geq K_1 t^c \quad (12)$$

Let $T > t_0$. We can always find $t > T$, $\theta \in (0, 1)$, such that :

$$v(t) \leq \theta K_1 t^c \quad (13)$$

Hence there exists $t > T$, $\theta \in (0, 1)$, s.t. :

$$t^2 W(t) = t^2|x(t)| \geq \underbrace{(1 - \theta)K_1}_{=K} t^c \quad (14)$$

□

Thank you for the Attention

For more details :

- Vassilis Apidopoulos, Jean-François Aujol and Charles Dossal. *The differential inclusion modeling FISTA algorithm and optimality of convergence rate in the case $b \leq 3$. Preprint, 2017.*

<https://hal.archives-ouvertes.fr/hal-01517708/>

- Vassilis Apidopoulos, Jean-François Aujol and Charles Dossal. *Convergence rate of inertial Forward-Backward algorithm beyond Nesterov's rule. Preprint, 2017.*

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