Large Congestion Games: Wardrop or Poisson?

Roberto Cominetti Universidad Adolfo Ibáñez

Based on joint work with:

Marco Scarsini (LUISS) Marc Schröder (RWTH Aachen) Nicolás Stier-Moses (Facebook)

Séminaire Français d'Optimisation July 8th, 2020

= 9Q@

イロト イポト イヨト イヨト

You are planning your commute route for tomorrow.

Not sure about your exact departure time, nor who might be on the road.



A congestion game with a random set of players !

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ▶

Introduction

Congestion games model strategic interactions under crowding externalities.



Games with *"many small players"* are frequently modeled as nonatomic games with a continuum of players.

In which sense is a continuous model close to the discrete system ?

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで

Introduction

Congestion games model strategic interactions under crowding externalities.



Games with *"many small players"* are frequently modeled as nonatomic games with a continuum of players.

In which sense is a continuous model close to the discrete system ?

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ▶

The answer depends on what we mean by "small players"...

- player *i* has a small load $w_i \approx 0$ to be transported with certainty
- player *i* has a unit load but is present with small probability $p_i \approx 0$

Each interpretation yields a different continuous limit.

Network Congestion Games — \mathscr{G}

We are given a graph (V, E) with

- a set of *edges* $e \in E$ with continuous non-decreasing costs $c_e : \mathbb{R}_+ \to \mathbb{R}_+$
- a set of *OD pairs* $t \in T$ with corresponding routes $r \in \mathscr{R}_t \subseteq 2^E$

• a set of *demands* $d_t \ge 0$ for each $t \in T$



◆□▶ ◆□▶ ◆三▶ ◆三▶ ◆□ ◆ ○ ◆

Network Congestion Games — *G*

We are given a graph (V, E) with

- a set of edges $e \in E$ with continuous non-decreasing costs $c_e : \mathbb{R}_+ \to \mathbb{R}_+$
- a set of *OD pairs* $t \in T$ with corresponding routes $r \in \mathscr{R}_t \subseteq 2^E$

• a set of *demands* $d_t \ge 0$ for each $t \in T$



Demands can be...

 \bullet non-atomic: continuous, infinitesimal players \rightarrow urban traffic

• atomic $\begin{cases} \text{splittable: continuous, few players} \rightarrow \text{fluids, sand, telecom} \\ \text{unsplittable: discrete, few players} \rightarrow \text{vessels, airplanes} \\ \text{random: unpredictable} \rightarrow \text{packets or vehicles on a network} \end{cases}$

◆ロト ◆□ → ◆目 → ◆目 → ● ● ● ●

Non-Atomic Congestion Games — \mathscr{G}^{na}

- Continuum of players / each one has a negligible impact on congestion.
- Perfectly divisible / aggregate demands $d_t \ge 0$ for each OD pair $t \in T$.

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ▶

Non-Atomic Congestion Games — \mathscr{G}^{na}

- Continuum of players / each one has a negligible impact on congestion.
- Perfectly divisible / aggregate demands $d_t \ge 0$ for each OD pair $t \in T$.

Let \mathscr{F} be the set of splittings (y, x) of the demands d_t into route-flows $y_r \ge 0$, together with their induced edge-loads x_e :

$$\begin{split} d_t &= \sum_{r \in \mathscr{R}_t} y_r \quad (\forall t \in T), \\ x_e &= \sum_{r \ni e} y_r \quad (\forall e \in E). \end{split}$$

◆□> ◆□> ◆豆> ◆豆> ・豆 ・ ��

Non-Atomic Congestion Games — \mathscr{G}^{na}

- Continuum of players / each one has a negligible impact on congestion.
- Perfectly divisible / aggregate demands $d_t \ge 0$ for each OD pair $t \in T$.

Let \mathscr{F} be the set of splittings (y, x) of the demands d_t into route-flows $y_r \ge 0$, together with their induced edge-loads x_e :

$$\begin{aligned} &d_t = \sum_{r \in \mathscr{R}_t} y_r \quad (\forall t \in T), \\ &x_e = \sum_{r \ni e} y_r \quad (\forall e \in E). \end{aligned}$$

A Wardrop equilibrium is a pair $(\hat{y}, \hat{x}) \in \mathscr{F}$ that uses only shortest routes:

$$(\forall t \in T)(\forall r, r' \in \mathscr{R}_t) \quad \hat{y}_r > 0 \Rightarrow \sum_{e \in r} c_e(\hat{x}_e) \le \sum_{e \in r'} c_e(\hat{x}_e).$$

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ▶

Example: Single OD with 2 identical parallel links.



At equilibrium the demand splits 50%-50% : $(\frac{d}{2}, \frac{d}{2})$.

・ロト ・ 同ト ・ ヨト ・ ヨト

= 990

Example: Single OD with 2 identical parallel links.



At equilibrium the demand splits 50%-50% : $(\frac{d}{2},\frac{d}{2})$.

Variational characterization:

Theorem (Beckmann-McGuire-Winsten, 1955)

Wardrop equilibria are exactly the optimal solutions of the convex program

$$\min_{(y,x)\in\mathscr{F}} \sum_{e\in E} \int_0^{x_e} c_e(z) \, dz.$$

・ロト ・ 同ト ・ ヨト ・ ヨト

Atomic Splittable Congestion Games — \mathscr{G}^s

Atomic splittable congestion games are similar in that demands are continuous and can be split over different routes, except that now:

- There are finitely many players, each one controls a fraction of the demand.
- Each player has a non-negligible impact on congestion and exploits her market power by strategically splitting the demand over the available routes.

◆□> ◆□> ◆臣> ◆臣> ―臣 - のへで

Atomic Splittable Congestion Games — \mathscr{G}^s

Atomic splittable congestion games are similar in that demands are continuous and can be split over different routes, except that now:

- There are finitely many players, each one controls a fraction of the demand.
- Each player has a non-negligible impact on congestion and exploits her market power by strategically splitting the demand over the available routes.

Theorem (Haurie & Marcotte, 1985)

When the number of players increases and the demand controlled by each of them tends to 0, the splittable equilibria converge to a Wardrop equilibrium.

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ▶

Atomic Splittable Congestion Games — \mathscr{G}^s

Atomic splittable congestion games are similar in that demands are continuous and can be split over different routes, except that now:

- There are finitely many players, each one controls a fraction of the demand.
- Each player has a non-negligible impact on congestion and exploits her market power by strategically splitting the demand over the available routes.

Theorem (Haurie & Marcotte, 1985)

When the number of players increases and the demand controlled by each of them tends to 0, the splittable equilibria converge to a Wardrop equilibrium.

In what follows we address the discrete cases: unsplittable and random demands.

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ▶

Weighted Congestion Games — $\mathscr{G}(w)$

A weighted congestion game has a finite set of players $i \in N$ with OD pairs $t_i \in T$, and unsplittable weights $w_i > 0$ that must be routed over a single path $r_i \in \mathscr{R}_{t_i}$ chosen at random using a mixed strategy $\pi_i \in \Delta(\mathscr{R}_{t_i})$.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Weighted Congestion Games — $\mathscr{G}(w)$

A weighted congestion game has a finite set of players $i \in N$ with OD pairs $t_i \in T$, and unsplittable weights $w_i > 0$ that must be routed over a single path $r_i \in \mathscr{R}_{t_i}$ chosen at random using a mixed strategy $\pi_i \in \Delta(\mathscr{R}_{t_i})$.

- $Y_r = \sum_{i \in N} w_i \mathbbm{1}_{\{r_i = r\}}$ are the random route-flows
- $X_e = \sum_{i \in N} w_i \mathbb{1}_{\{e \in r_i\}}$ are the corresponding edge-loads

Weighted Congestion Games — $\mathscr{G}(w)$

A weighted congestion game has a finite set of players $i \in N$ with OD pairs $t_i \in T$, and unsplittable weights $w_i > 0$ that must be routed over a single path $r_i \in \mathscr{R}_{t_i}$ chosen at random using a mixed strategy $\pi_i \in \Delta(\mathscr{R}_{t_i})$.

- $Y_r = \sum_{i \in N} w_i \mathbbm{1}_{\{r_i = r\}}$ are the random route-flows
- $X_e = \sum_{i \in N} w_i \, \mathbbm{1}_{\{e \in r_i\}}$ are the corresponding edge-loads

A mixed strategy profile $\pi = (\pi_i)_{i \in N}$ is a Nash equilibrium iff for each player $i \in N$ and routes $r, r' \in \mathscr{R}_{t_i}$ with $\pi_i(r) > 0$ we have

$$\mathbb{E}\left[\sum_{e \in r} c_e(X_e) | r_i = r\right] \le \mathbb{E}\left[\sum_{e \in r'} c_e(X_e) | r_i = r'\right]$$

◆ロ > ◆母 > ◆臣 > ◆臣 > ― 臣 ― のへで

• WCGs with identical weights $w_i \equiv w$ are potential games and admit pure equilibria (Rosenthal'73). The potential for a profile $\mathbf{r} = (r_i)_{i \in N}$ is

$$\Phi(\mathbf{r}) = \sum_{e \in E} \sum_{k=1}^{n_e(\mathbf{r})} c_e(kw) w \qquad ; \qquad n_e(\mathbf{r}) \triangleq |\{i \in N : e \in r_i\}|.$$

• For heterogeneous weights we only have the existence of mixed equilibria.

◆□> ◆□> ◆豆> ◆豆> ・豆 ・ ��

Example: Routing *n* players over 2 identical parallel links.



Symmetric mixed equilibrium: each player randomizes $(\frac{1}{2}, \frac{1}{2})$.

Example: Routing *n* players over 2 identical parallel links.



Symmetric mixed equilibrium: each player randomizes $(\frac{1}{2}, \frac{1}{2})$.

If players' weights are $w_i \equiv d/n$ then we have random edge-loads

$$X_e \sim \frac{d}{n} \operatorname{Binomial}(n, \frac{1}{2})$$

which converge almost surely to the Wardrop equilibrium $(\frac{d}{2}, \frac{d}{2})$.

イロト イヨト イヨト イヨト

Sar

Example: Routing *n* players over 2 identical parallel links.



Symmetric mixed equilibrium: each player randomizes $(\frac{1}{2}, \frac{1}{2})$.

If players' weights are $w_i \equiv d/n$ then we have random edge-loads

 $X_e \sim \frac{d}{n} \operatorname{Binomial}(n, \frac{1}{2})$

which converge almost surely to the Wardrop equilibrium $(\frac{d}{2}, \frac{d}{2})$.

What happens for other non-symmetric equilibria? What if weights are not homogeneous? And with different costs? And more complex topologies?

◆□▶ ◆□▶ ◆三▶ ◆三▶ ・三 ・ つへで

Wardrop Convergence for Vanishing Weights

Let π^n be a sequence of mixed equilibria for weighted ACGs $\mathscr{G}(w^n)$ with

$$\begin{cases} a) & |N^n| \to \infty \\ b) & \max_{i \in N^n} w_i^n \to 0 \\ c) & d_t^n \triangleq \sum_{i:t_i^n = t} w_i^n \to d_t \quad \text{for all } t \in T \end{cases}$$

イロト イポト イヨト イヨト

Wardrop Convergence for Vanishing Weights

Let π^n be a sequence of mixed equilibria for weighted ACGs $\mathscr{G}(w^n)$ with

$$egin{array}{ll} egin{array}{ll} |\mathcal{N}^n| o \infty \ b) & \max_{i \in \mathcal{N}^n} w_i^n o 0 \ c) & d_t^n riangleq \sum_{i:t_i^n = t} w_i^n o d_t & ext{for all } t \in T \end{array}$$

Theorem

The expected flows (yⁿ, xⁿ) = (EYⁿ, EXⁿ) are bounded and each cluster point (ŷ, x̂) is a Wardrop equilibrium with demands d_t and costs c_e(·).

= nar

▲ロ → ▲園 → ▲ 臣 → ▲ 臣 → □ ● □ - の Q ()

Wardrop Convergence for Vanishing Weights

Let π^n be a sequence of mixed equilibria for weighted ACGs $\mathscr{G}(w^n)$ with

$$egin{array}{ll} egin{array}{ll} |\mathcal{N}^n| o \infty \ b) & \max_{i \in \mathcal{N}^n} w_i^n o 0 \ c) & d_t^n riangleq \sum_{i:t_i^n = t} w_i^n o d_t & ext{for all } t \in T \end{array}$$

Theorem

- The expected flows (yⁿ, xⁿ) = (EYⁿ, EXⁿ) are bounded and each cluster point (ŷ, x̂) is a Wardrop equilibrium with demands d_t and costs c_e(·).
- Along any convergent subsequence, the random route-flows and edge-loads (Yⁿ, Xⁿ) converge in L² to the (constant) Wardrop equilibrium (ŷ, x̂).

◆□ → ◆□ → ◆ □ → ◆ □ → ◆ □ → ◆ ○ ◆

Wardrop Convergence for Vanishing Weights

Let π^n be a sequence of mixed equilibria for weighted ACGs $\mathscr{G}(w^n)$ with

$$egin{array}{ll} egin{array}{ll} |\mathcal{N}^n| o \infty \ b) & \max_{i \in \mathcal{N}^n} w_i^n o 0 \ c) & d_t^n riangleq \sum_{i:t_i^n = t} w_i^n o d_t & ext{for all } t \in T \end{array}$$

Theorem

- The expected flows (yⁿ, xⁿ) = (EYⁿ, EXⁿ) are bounded and each cluster point (ŷ, x̂) is a Wardrop equilibrium with demands d_t and costs c_e(·).
- Along any convergent subsequence, the random route-flows and edge-loads (Yⁿ, Xⁿ) converge in L² to the (constant) Wardrop equilibrium (ŷ, x̂).
- If the costs $c_e(\cdot)$ are strictly increasing, then \hat{x} is unique and $X^n \xrightarrow{L^2} \hat{x}$.

Wardrop Convergence for Vanishing Weights

Let π^n be a sequence of mixed equilibria for weighted ACGs $\mathscr{G}(w^n)$ with

$$egin{array}{ll} egin{array}{ll} |\mathcal{N}^n| o \infty \ b) & \max_{i \in \mathcal{N}^n} w_i^n o 0 \ c) & d_t^n riangleq \sum_{i:t_i^n = t} w_i^n o d_t & ext{for all } t \in T \end{array}$$

Theorem

- The expected flows (yⁿ, xⁿ) = (EYⁿ, EXⁿ) are bounded and each cluster point (ŷ, x̂) is a Wardrop equilibrium with demands d_t and costs c_e(·).
- Along any convergent subsequence, the random route-flows and edge-loads (Yⁿ, Xⁿ) converge in L² to the (constant) Wardrop equilibrium (ŷ, x̂).
- If the costs $c_e(\cdot)$ are strictly increasing, then \hat{x} is unique and $X^n \xrightarrow{L^2} \hat{x}$.
- If $c_e \in C^2$ with $c'_e(\cdot) > 0$, then there is a constant κ such that

$$\|X^n - \hat{x}\|_{L^2} \leq \kappa (\sqrt{\max_{i \in N} w_i^n} + \sqrt{\|d^n - d\|_1}).$$

Simple and expected... but reality looks more like this

Copenhagen – Source: DTU Transport (www.transport.dtu.dk)



Figure 7: Observations of travel time by time of day. Frederikssundsvej, inward direction



Traffic count data - Dublin 2017-2018



◆□ > ◆□ > ◆臣 > ◆臣 > 善臣 - 釣��

Bernoulli Congestion Games — $\mathscr{G}(p)$

A *Bernoulli congestion game* has a finite set of players $i \in N$ with OD pairs $t_i \in T$, unit weights $w_i = 1$, and a probability of being active

$$p_i = \mathbb{P}(U_i = 1).$$

Each player $i \in N$ selects a route $r_i \in \mathscr{R}_{t_i}$ using a mixed strategy $\pi_i \in \Delta(\mathscr{R}_{t_i})$.

Bernoulli Congestion Games — $\mathscr{G}(p)$

A *Bernoulli congestion game* has a finite set of players $i \in N$ with OD pairs $t_i \in T$, unit weights $w_i = 1$, and a probability of being active

$$p_i = \mathbb{P}(U_i = 1).$$

Each player $i \in N$ selects a route $r_i \in \mathscr{R}_{t_i}$ using a mixed strategy $\pi_i \in \Delta(\mathscr{R}_{t_i})$.

- $Y_r = \sum_{i \in N} U_i \mathbb{1}_{\{r_i = r\}}$ are the random route-flows
- $X_e = \sum_{i \in N} U_i \mathbb{1}_{\{e \in r_i\}}$ are the corresponding edge-loads

◆□ > ◆□ > ◆豆 > ◆豆 > ̄豆 = ∽ Q Q @

Bernoulli Congestion Games — $\mathscr{G}(p)$

A *Bernoulli congestion game* has a finite set of players $i \in N$ with OD pairs $t_i \in T$, unit weights $w_i = 1$, and a probability of being active

$$p_i = \mathbb{P}(U_i = 1).$$

Each player $i \in N$ selects a route $r_i \in \mathscr{R}_{t_i}$ using a mixed strategy $\pi_i \in \Delta(\mathscr{R}_{t_i})$.

• $Y_r = \sum_{i \in N} U_i \mathbb{1}_{\{r_i = r\}}$ are the random route-flows • $X_e = \sum_{i \in N} U_i \mathbb{1}_{\{e \in r_i\}}$ are the corresponding edge-loads

A strategy profile $\pi = (\pi_i)_{i \in N}$ is a Bayes-Nash equilibrium if for each player $i \in N$ and routes $r, r' \in \mathscr{R}_{t_i}$ with $\pi_i(r) > \overline{0}$ we have

$$\mathbb{E}\left[\sum_{e \in r} c_e(X_e) | U_i = 1, r_i = r\right] \leq \mathbb{E}\left[\sum_{e \in r'} c_e(X_e) | U_i = 1, r_i = r'\right].$$

REMARK. Costs need only be defined over the integers $c_e : \mathbb{N} \to \mathbb{R}_+$.

(ロ)、(型)、(E)、(E)、 E のQで

イロト イボト イヨト イヨト

Bernoulli ACGs are Potential Games

Proposition

Every Bernoulli ACG is a potential game with potential

$$\Phi(\mathbf{r}) \triangleq \mathbb{E}\left[\sum_{e \in E} \sum_{k=1}^{N_e(\mathbf{r})} c_e(k)\right] \quad ; \quad N_e(\mathbf{r}) \triangleq \sum_{i:e \in r_i} U_i$$

Corollary

Every Bernoulli ACG has Nash equilibria in pure strategies.

Э

Example: Routing *n* random players over 2 identical parallel links.



Symmetric mixed equilibrium: each player randomizes $(\frac{1}{2}, \frac{1}{2})$.

◆□ → ◆□ → ◆ □ → ◆ □ → ◆ □ → ◆ ○ ◆

Example: Routing *n* random players over 2 identical parallel links.



Symmetric mixed equilibrium: each player randomizes $(\frac{1}{2}, \frac{1}{2})$.

If each player is present with probability $p_i = d/n$, the random edge-loads are

 $X_e \sim \text{Binomial}(n, \frac{d}{2n})$

which for large *n* converges to a Poisson $(\frac{d}{2})$.

◆□ → ◆□ → ◆ □ → ◆ □ → ◆ □ → ◆ ○ ◆

Example: Routing *n* random players over 2 identical parallel links.



Symmetric mixed equilibrium: each player randomizes $(\frac{1}{2}, \frac{1}{2})$.

If each player is present with probability $p_i = d/n$, the random edge-loads are

 $X_e \sim \text{Binomial}(n, \frac{d}{2n})$

which for large *n* converges to a Poisson $(\frac{d}{2})$.

What happens for other non-symmetric equilibria? What if players are not homogeneous? And with different costs? And more complex topologies?

◆□▶ ◆□▶ ◆三▶ ◆三▶ ・三 ・ つへで

Toolkit — Sums of Bernoullis \approx Poisson

The total variation distance between two integer-valued random variables U, V is

$$d_{\mathrm{TV}}(U, V) = \frac{1}{2} \sum_{k \in \mathbb{N}} |\mathbb{P}(U=k) - \mathbb{P}(V=k)|.$$

Theorem (Barbour & Hall 1984, Borizov & Ruzankin 2002))

Let $S = X_1 + \ldots + X_n$ be a sum of independent Bernoullis with $\mathbb{P}(X_i = 1) \le p$, and $X \sim \text{Poisson}(x)$ with the same expectation $\mathbb{E}[X] = x = \mathbb{E}[S]$. Then

 $d_{TV}(S,X) \leq p.$

Moreover, if $h : \mathbb{N} \to \mathbb{R}$ is such that $\mathbb{E}|\Delta^2 h(X)| \leq \nu$, then

$$|\mathbb{E}h(S) - \mathbb{E}h(X)| \leq \frac{x\nu}{2} \frac{p e^{p}}{(1-p)^2}.$$

REMARK: $\Delta^2 h(x) \triangleq h(x+2) - 2h(x+1) + h(x)$.

→ ▲□ → ▲目 → ▲目 → ▲□ → への

Poisson Convergence for Vanishing Probabilities

Standing Assumption: $\mathbb{E}[X^2c_e(1+X)] < \infty$ for all $e \in E$ and $X \sim \text{Poisson}(x)$.

This is a mild condition. It holds for costs with polynomial or exponential growth. It fails for fast growing costs such as factorials k! or bi-exponentials $\exp(\exp(k))$.

We introduce the expected cost functions $\tilde{c}_e : \mathbb{R}_+ \to \mathbb{R}_+$ defined by

$$\widetilde{c}_e(x) \triangleq \mathbb{E}[c_e(1+X)] = \sum_{k=0}^{\infty} c_e(1+k)e^{-x\frac{x^k}{k!}}.$$

◆□ > ◆□ > ◆臣 > ◆臣 > 善臣 - 釣��

Poisson Convergence for Vanishing Probabilities

Let π^n be a sequence of Bayes-Nash equilibria for Bernoulli ACGs $\mathscr{G}(p^n)$ with

$$\begin{cases} a) & |\mathcal{N}^n| \to \infty, \\ b) & \max_{i \in \mathcal{N}^n} p_i^n \to 0, \\ c) & d_t^n \triangleq \sum_{i:t_i^n = t} p_i^n \to d_t \quad \text{for all } t \in \mathcal{T}. \end{cases}$$

Poisson Convergence for Vanishing Probabilities

Let π^n be a sequence of Bayes-Nash equilibria for Bernoulli ACGs $\mathscr{G}(p^n)$ with

$$\begin{cases} a) & |\mathcal{N}^n| \to \infty, \\ b) & \max_{i \in \mathcal{N}^n} p_i^n \to 0, \\ c) & d_t^n \triangleq \sum_{i: t_i^n = t} p_i^n \to d_t \quad \text{for all } t \in \mathcal{T}. \end{cases}$$

Theorem

The expected flows (yⁿ, xⁿ) = (EYⁿ, EXⁿ) are bounded and each cluster point (ỹ, x̃) is a Wardrop equilibrium with demands d_t and costs c̃_e(·).

Sar

イロン 不良 とくほう 不良 とうほう

Poisson Convergence for Vanishing Probabilities

Let π^n be a sequence of Bayes-Nash equilibria for Bernoulli ACGs $\mathscr{G}(p^n)$ with

$$\begin{cases} a) & |N^n| \to \infty, \\ b) & \max_{i \in N^n} p_i^n \to 0, \\ c) & d_t^n \triangleq \sum_{i:t_i^n = t} p_i^n \to d_t & \text{for all } t \in T. \end{cases}$$

Theorem

- The expected flows (yⁿ, xⁿ) = (EYⁿ, EXⁿ) are bounded and each cluster point (ỹ, x̃) is a Wardrop equilibrium with demands d_t and costs c̃_e(·).
- Along any convergent subsequence we have
 - the edge-loads X_e^n converge in total variation to $X_e \sim Poisson(\tilde{x}_e)$,
 - the route-flows Y_r^n converge in total variation to $Y_r \sim Poisson(\tilde{y}_r)$,
 - the Poisson limits Y_r are independent.

DQC

イロト イポト イヨト イヨト

Poisson convergence for vanishing probabilities

Corollary

If the costs $c_e(k)$ are non-decreasing and non-constant, then the $\tilde{c}_e(\cdot)$'s are strictly increasing, the edge-loads \tilde{x}_e are the same in all Wardrop equilibria, and for every sequence π^n of Bayes-Nash equilibria we have

$$X_e^n \stackrel{\mathrm{TV}}{\longrightarrow} X_e \sim \textit{Poisson}(\tilde{x}_e).$$

Sar

Poisson convergence for vanishing probabilities

Corollary

If the costs $c_e(k)$ are non-decreasing and non-constant, then the $\tilde{c}_e(\cdot)$'s are strictly increasing, the edge-loads \tilde{x}_e are the same in all Wardrop equilibria, and for every sequence π^n of Bayes-Nash equilibria we have

$$X_e^n \stackrel{\mathrm{TV}}{\longrightarrow} X_e \sim \textit{Poisson}(ilde{x}_e).$$

Theorem

If $c_e(2) > c_e(1)$ for all $e \in E$ then there is a constant κ such that

$$d_{TV}(X_e^n, X_e) \leq \kappa(\sqrt{\max_{i \in N} p_i^n} + \sqrt{\|d^n - d\|_1}).$$

Sar

◆□ > ◆□ > ◆豆 > ◆豆 > ̄豆 = ∽ Q Q @

- **(**) Both $w_i^n \to 0$ and $p_i^n \to 0$ lead to different non-atomic limit games:
 - For vanishing weights, the random edge-loads X_e^n converge in L^2 to the constants edge-loads \hat{x}_e .
 - For vanishing probabilities, X_e^n remain random in the limit and converge in total variation to $X_e \sim \text{Poisson}(\tilde{x}_e)$.

◆□ > ◆□ > ◆臣 > ◆臣 > 善臣 - 釣��

- **(**) Both $w_i^n \to 0$ and $p_i^n \to 0$ lead to different non-atomic limit games:
 - For vanishing weights, the random edge-loads X_e^n converge in L^2 to the constants edge-loads \hat{x}_e .
 - For vanishing probabilities, X_e^n remain random in the limit and converge in total variation to $X_e \sim \text{Poisson}(\tilde{x}_e)$.
- The Poisson limit is consistent with empirical data on traffic counts. Also pⁿ_i → 0 is quite natural... congestion depends on players that are present on a small window around your departure time.

▲□▶▲□▶▲□▶▲□▶ = つへで

- **9** Both $w_i^n \to 0$ and $p_i^n \to 0$ lead to different non-atomic limit games:
 - For vanishing weights, the random edge-loads X_e^n converge in L^2 to the constants edge-loads \hat{x}_e .
 - For vanishing probabilities, Xⁿ_e remain random in the limit and converge in total variation to X_e ~ Poisson(x̃_e).
- The Poisson limit is consistent with empirical data on traffic counts. Also pⁿ_i → 0 is quite natural... congestion depends on players that are present on a small window around your departure time.
- The Poisson limit is a special case of Myerson's Poisson games: the normalized loads $\sigma(r|t) = y_r/d_t$ for $r \in \mathscr{R}_t$ yield an equilibrium in the Poisson game (Int J Game Theory 1998).

◆□ > ◆□ > ◆臣 > ◆臣 > 善臣 - 釣��

- **9** Both $w_i^n \to 0$ and $p_i^n \to 0$ lead to different non-atomic limit games:
 - For vanishing weights, the random edge-loads X_e^n converge in L^2 to the constants edge-loads \hat{x}_e .
 - For vanishing probabilities, Xⁿ_e remain random in the limit and converge in total variation to X_e ~ Poisson(x̃_e).
- The Poisson limit is consistent with empirical data on traffic counts. Also pⁿ_i → 0 is quite natural... congestion depends on players that are present on a small window around your departure time.
- The Poisson limit is a special case of Myerson's Poisson games: the normalized loads $\sigma(r|t) = y_r/d_t$ for $r \in \mathscr{R}_t$ yield an equilibrium in the Poisson game (Int J Game Theory 1998).
- Poisson games were defined without reference to a limit process, so our convergence result as well as the connection with Wardrop seem new.



- Nonatomic games and Wardrop equilibria
- Weighted atomic games \longrightarrow Wardop equilibrium
- Games with random players \longrightarrow Poisson equilibrium

Price-of-Anarchy in Atomic Congestion Games

- Convergence of PoA along sequences of ACGs
- PoA for Bernoulli ACGs
- PoA for ACGs with affine costs
- Price-of-Stability

イロト イポト イヨト イヨト

Sar

Convergence of PoA along sequences of ACGs

For an atomic congestion game ${\mathscr G}$ we denote

$$C(\pi) = \mathbb{E}_{\pi} \left[\sum_{e \in E} X_e c_e(X_e) \right]$$
(expected social cost)

$$C_{opt}(\mathscr{G}) = \min_{\pi} C(\pi)$$
(minimum social cost)

$$PoA(\mathscr{G}) = \max_{\pi \in \mathscr{E}(\mathscr{G})} C(\pi) / C_{opt}(\mathscr{G})$$
(price-of-anarchy)

◆□ > ◆□ > ◆豆 > ◆豆 > ̄豆 = ∽ Q Q @

イロト イポト イヨト イヨト

Convergence of PoA along sequences of ACGs

For an atomic congestion game ${\mathscr G}$ we denote

$$C(\pi) = \mathbb{E}_{\pi} \left[\sum_{e \in E} X_e c_e(X_e) \right]$$
(expected social cost)

$$C_{opt}(\mathscr{G}) = \min_{\pi} C(\pi)$$
(minimum social cost)

$$PoA(\mathscr{G}) = \max_{\pi \in \mathscr{E}(\mathscr{G})} C(\pi) / C_{opt}(\mathscr{G})$$
(price-of-anarchy)

Theorem

Under the same conditions of the convergence theorems for weighted and Bernoulli ACGs, we have

$$\operatorname{PoA}(\mathscr{G}(w^n)) \longrightarrow \operatorname{PoA}(Wardrop)$$

 $\operatorname{PoA}(\mathscr{G}(p^n)) \longrightarrow \operatorname{PoA}(Poisson)$

Sar

PoA for Bernoulli ACGs — Homogeneous players

How does PoA behaves as a function of the probabilities p_i ?

Theorem

Let \mathscr{G}^p denote the set of Bernoulli ACGs with $p_i \leq p$ for all players. The largest values of $\operatorname{PoA}(\mathscr{G}(p))$ occur for homogeneous players with $p_i \equiv p$.

◆ロ ▶ ◆ 同 ▶ ★ 臣 ▶ ★ 臣 ▶ → 臣 → の Q @

PoA for Bernoulli ACGs — Homogeneous players

How does PoA behaves as a function of the probabilities p_i ?

Theorem

Let \mathscr{G}^p denote the set of Bernoulli ACGs with $p_i \leq p$ for all players. The largest values of $\operatorname{PoA}(\mathscr{G}(p))$ occur for homogeneous players with $p_i \equiv p$.

From now on we focus on the homogeneous case and study PoA and PoS as a function of p when we move from the deterministic case p = 1 to the limit $p \downarrow 0$.

$$\begin{aligned} \operatorname{PoA}(p) &= \sup_{\mathscr{G}^{p}} \max_{\pi \in \mathscr{E}(\mathscr{G}^{p})} C(\pi) / C_{opt}(\mathscr{G}^{p}) & (\operatorname{Price-of-Anarchy}) \\ \operatorname{PoS}(p) &= \sup_{\mathscr{G}^{p}} \min_{\pi \in \mathscr{E}(\mathscr{G}^{p})} C(\pi) / C_{opt}(\mathscr{G}^{p}) & (\operatorname{Price-of-Stability}) \end{aligned}$$

◆ロ ▶ ◆ □ ▶ ★ □ ▶ ★ □ ▶ → □ ■ → の < ○

Related Literature

- Related models
 - Non-atomic with stochastic demand (Wang, Doan and Chen, 2014; Correa, Hoeksma and Schröder, 2019)
 - Smoothness with incomplete information (Roughgarden, 2015)
 - Perception based (Kleer and Schäfer, 2018)

Related Literature

- Related models
 - Non-atomic with stochastic demand (Wang, Doan and Chen, 2014; Correa, Hoeksma and Schröder, 2019)
 - Smoothness with incomplete information (Roughgarden, 2015)
 - Perception based (Kleer and Schäfer, 2018)
- PoA for congestion games with affine costs
 - $\operatorname{PoA}(\mathscr{G}) \leq \frac{4}{3}$ for non-atomic (Roughgarden and Tardos, 2002)
 - $PoA(\mathscr{G}) \leq \frac{5}{2}$ for atomic deterministic (Christodoulou and Koutsoupias, 2005; Awerbuch, Azar and Epstein, 2005)

Related Literature

- Related models
 - Non-atomic with stochastic demand (Wang, Doan and Chen, 2014; Correa, Hoeksma and Schröder, 2019)
 - Smoothness with incomplete information (Roughgarden, 2015)
 - Perception based (Kleer and Schäfer, 2018)
- PoA for congestion games with affine costs
 - $\operatorname{PoA}(\mathscr{G}) \leq \frac{4}{3}$ for non-atomic (Roughgarden and Tardos, 2002)
 - $PoA(\mathscr{G}) \leq \frac{5}{2}$ for atomic deterministic (Christodoulou and Koutsoupias, 2005; Awerbuch, Azar and Epstein, 2005)

As a consequence of the latter we get $\operatorname{PoA}(p) \leq \frac{5}{2}$.

But we can find sharper bounds... and we expect $\operatorname{PoA}(p) \sim \frac{4}{3}$ for small p.

<ロト < 課 > < 注 > < 注 > 」 注 の < @</p>

Smoothness Framework

Proposition

A Bernoulli ACG with homogeneous players is equivalent to a deterministic unweighted ACG for the auxiliary costs

 $c_e^p(k) = \mathbb{E}[c_e(1+B)]$ with $B \sim \text{Binomial}(k-1, p)$

Smoothness Framework

Proposition

A Bernoulli ACG with homogeneous players is equivalent to a deterministic unweighted ACG for the auxiliary costs

 $c_e^p(k) = \mathbb{E}[c_e(1+B)]$ with $B \sim \text{Binomial}(k-1, p)$

Lemma (Roughgarden, 2015)

Let \mathscr{G} be an unweighted ACG which is (λ, μ) -smooth with $\lambda > 0$ and $\mu \in (0, 1)$, that is to say

$$(\forall s, s' \in S) \quad \sum_{i \in N} C_i(s'_i, s_{-i}) \leq \lambda C(s') + \mu C(s).$$

Then we have $\operatorname{PoA}(\mathscr{G}) \leq \frac{\lambda}{1-u}$.

イロン 不良 とくほう 不良 とうほう

Smoothness Framework — Affine Costs

Lemma

Let $\mathscr{P} = \{(k,m) \in \mathbb{N}^2 : k \geq 1\}$ and suppose that $\lambda > 0$ and $\mu \in (0,1)$ satisfy

$$k(1+pm) \leq \lambda k(1-p+pk) + \mu m(1-p+pm) \quad \forall (k,m) \in \mathscr{P}.$$
 (1)

Then every stochastic ACG \mathscr{G}^p with homogeneous players and affine costs is (λ, μ) -smooth, and therefore $\operatorname{PoA}(p) \leq \frac{\lambda}{1-\mu}$.

◆ロ> ◆母> ◆臣> ◆臣> ―臣 - のへで

Smoothness Framework — Affine Costs

Lemma

Let $\mathscr{P} = \{(k,m) \in \mathbb{N}^2 : k \geq 1\}$ and suppose that $\lambda > 0$ and $\mu \in (0,1)$ satisfy

$$k(1+pm) \leq \lambda k(1-p+pk) + \mu m(1-p+pm) \quad \forall (k,m) \in \mathscr{P}.$$
 (1)

Then every stochastic ACG \mathscr{G}^{p} with homogeneous players and affine costs is (λ, μ) -smooth, and therefore $\operatorname{PoA}(p) \leq \frac{\lambda}{1-\mu}$.

The best combination of λ and μ for fixed *p* requires to solve

$$B(p) \triangleq \min_{\lambda > 0, \mu \in (0,1)} \left\{ \frac{\lambda}{1-\mu} : \text{ subject to } (1) \right\}$$

which reduces to a 1D problem noting that the smallest λ compatible with (1) is

$$\lambda = \sup_{(k,m)\in\mathscr{P}} \frac{k(1+pm)-\mu m(1-p+pm)}{k(1-p+pk)}$$

Smoothness Framework — Affine Costs

The previous reduction leads to the equivalent minimization problem

$$B(p) = \inf_{\mu \in (0,1)} \varphi_p(\frac{\mu}{1-\mu}) = \inf_{y>0} \varphi_p(y)$$

where $\varphi_p(\cdot)$ is the convex envelop function

$$\varphi_p(y) = \sup_{(k,m)\in\mathscr{P}} \frac{1+pm}{1-p+pk} + \frac{k(1+pm)-m(1-p+pm)}{k(1-p+pk)} y.$$

For each p the unique optimum y can be found explicitly, and then we recover the optimal combination (λ, μ) .

<ロト < 課 > < 注 > < 注 > 」 注 の < @</p>

Upper Bounds for the Price-of-Anarchy

Theorem

Set $\bar{p}_0=\frac{1}{4}$ and $\bar{p}_1\sim 0.3774$ the unique real root of $8p^3+4p^2=1.$ Then

$$\Rightarrow \qquad \operatorname{PoA}(p) \le B(p) = \begin{cases} 4/3 & \text{if } 0$$



Lower Bounds for Large p



・ロト ・回ト ・ヨト ・ヨト

Lower Bounds for Small p



Lower Bounds for Intermediate p



Bounds on the Price-of-Anarchy are Tight



(Roberto Cominetti - UAI)

Price-of-Anarchy vs Price-of-Stability

Combining with Kleer and Schäfer (2018), we also get tight bounds for PoS



Conclusion

- Convergence of ACGs towards non-atomic games:
 - $\bullet \ \ \text{vanishing weights} \longrightarrow \text{Wardrop}$
 - vanishing probabilities \longrightarrow Poisson/Wardrop
- Onvergence of PoA/PoS, plus sharp bounds for affine costs
- Some open questions
 - Mixed limits: weights & probabilities
 - Tight bounds for polynomial costs

<□> <同> <同> < 目> < 目> < 目> = - のへで



Thanks ! Questions ?

◆□ > ◆□ > ◆臣 > ◆臣 > ─臣 ─ のへで